

To Enhance Security & Efficiency of VANET Routing Protocol using VWCA

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Abstract:- Vehicular network are receiving a lot of attention due to the wide variety of services they can provide. Their applications range from safety and crash avoidance to internet access and multimedia. A lot of work search around the globe is being conducted to define the standards for vehicular communications. These include frequency allocations, standards for physical and link layers routing algorithm, as well as security issues and new applications. In this paper we review the standardization work and researches related to vehicular networks and discuss the challenges facing future vehicular networks. VANETs have become an intriguing field of study since vehicles capable of having detectors, processing and communication devices. Consequently, several lives changing software surfaced in various areas such as society and security services. VANETs are considered A kind of emergency category networks. However, It possess unique qualities. That differentiates they appreciate Bandwidth requirements, privacy, security & excellent versatility of nodes. This paper discusses VANET's special characteristics and explains why VANETs are considered a subcategory of ad hoc networks. Also, A grouping of VANETs architectures shows itself here study. The worth of VANETs will and their requirements, together with their The programmes show up in this study. Furthermore Multiple protocols for routing proposed for Studying and categorising Virtual Area Networks for this work, protocols are given.

Keywords:- VANET, VWCA, and Sensor Coverage Vehicle ad-hoc Networking, Generalized C Methods, Q- LEACH, IEEE 802.11p Procedure, Energy use, and Connection Delay.

I. INTRODUCTION

VANETs are networks of fast-moving cars that interact with one other, with RSUs (V2R), with architecture (V2I), as well as other cars (V2V). Real-time information may be learned using wireless connections. [1- 2]. The RSU is situated at strategic areas such as gas pumps, slick roads, risky crossroads, etc. [3]. Road protection, navigation, data sources, user interactions, shared traffic, cooperative driving aid, road conditions, and other applications are available through the VANET. [4]. a cluster-based protocol that is utilised in VANET for efficient data transfer. The cluster created for data transmission among social networking (SN) within the cluster and between clusters created for RSU [5]. Dedicated VANET systems used the Short Distant Interaction Protocol

(DSRC). To increase both capacity and delay for V2V communications. Risen, making VANETs a popular technology.

The 1000 m DSRC, which bandwidth is appropriate for both V2V and V2I [6-8]. the Prospective Modification algorithm's prediction of the movement of the vehicles. Predictive For selecting the top groups of the VANETs, as grouping had been applied.[9]. Cross-layer routing enables communication of data across levels for better network performance while merely routing methods rely on the established layered network routing paradigm [10].several a greater number of sensors for sensors, Robotic dispersion takes a lot of the clock, unsuccessful. In regions with uneven elevation, this problem becomes more complicated. The use of detectors has attracted a lot of attention lately.

In very a VANET, safety is provided by the V2V multi hop dispersion and careful choice of intermediary nodes, which are which results in a high delivery ratio. Here, by arranging the nodes according to their unique abilities, unnecessary transmissions were prevented [11]. To transfer the data across the cars, an authentication code for the message and a lightweight symmetric encryption are needed [12]. Probabilistic coalition games and learning automata (LA) were used in the handheld video monitoring system to increase economy and prevent crashes. Here, the path score is used to generate the route[13]. The quick randomised pyramidal clustering algorithm (VWCA) creates reliable communication over the nodes, while the scheduling method manages channel access [14]. The employed area cognizant routing system includes density of vehicles The trust-based authorization system produced the cluster-based VANET systems topology [15].To establish namely chapters are chosen, the anticipated belief extent comprised of oblique and immediate believed extent, is employed. [16].

➤ *The following is a List of this Investigation's main Contributions:*

- By combining the FCM [17] and Q- LEACH [18] clustering techniques, a hybrid clustering approach minimised the electricity usage of the VANET architecture. This sort of clustering helps improve the efficiency of the link.
- The successful CH discovered by clustering. The CH gathers the data that it gets from numerous node sensors. This information is then sent to the Hdd.

- The DSRC, or IEEE 802.11.p [19], was implemented in this case reduce the latency on communication. The condition of the highways and cars is tracked by sending data from Rrc to BS..

II. LITERATURE REVIEW

The Medium Access Control (MAC) layer attributes in the safety vehicular ad-hoc networks were reported by Razvan Stanica et al. [20]. Utilising Direct V2V connection, an effective Intelligent Transportation System (ITS) was created. VANETs' MAC layer concerns are given particular attention by ITS and communications over vehicles. The vehicular MAC layer broadcasts the safety messages (such as lifespan) and the metrics pertaining to the safety context. New protocols and processes for the future vehicular network will be aided by V2V communications.

Segmentation and Conditional Blasting (CPB) is a data transmission strategy that was established by Lei Liu et al. [21]. Taking into account the direction and positioning of the vehicle, clustering was carried out. As a result of the distributed decision-making process used here, the clustering management overhead was lowered for each vehicle's choice of CH. Based on the traffic situation and vehicle density, the forwarding probability of each car was determined. The message transmission ratio changes as the its speed increases.

An approach for transmission routing that utilised contention was demonstrated by Michele Rondinone et al. Various simulcast forwarding rules, it is used to decide whether to transmit peace, requires the capacity to shift particles throughout the initial attachment nodes. path. A excellent packet delivery ratio was offered by the topology-aware contention-based forwarding method, which also reduced the amount of broadcasts over a network. This approach falls short in explaining route discovery.

An approach to multi-hop cross-layer action-based forwarding for VANETs was given by Sabihur Rehman et al. [23]. To reduce the routing objectives, the routing method

employed queue buffer information and beaconing information at a MAC layer. This routing protocol occasionally included information about other layer queues and channel quality to convey the information. This work does not cover the ideal channel integrity indicator values and queuing information for all vehicle contexts under genuine channel scenarios.

Since the RSU and automobiles only have a limited communication range, G. G. Md. Nawaz Ali et al. [24] introduced the Cooperative Load Balancing (CLB) between the RSUs that utilised their residual capacity to reduce the request drop rate. Therefore, the remaining delay tolerance and understanding of the set road layout are taken into account here in CLB, referred as Systems for V2I communication use enhanced CLB (ECLB). When the vehicle's route changed while transporting information to the destination, the overburdened load was readjusted. The amount of energy used and the quantity of messages transmitted successfully to the recipient are not covered in this work.

The strategies outlined previously offer certain drawbacks, such as difficulties with route finding and stream limitations. In this instance, these issues are resolved using the FCM-Q LEACH-VANET approach, while subsequent sections provide a detailed explanation of this approach.

III. FDQ LEACH-VANET

VANETs may often be divided/partitioned into clusters. A cluster of machines is a collection of SNs whereby each pair of nodes is connected by more than one hop. Here, VANET filtering is accomplished by fusing FCM with Q LEACH clustering. This sort of clustering helps enhance the efficiency of the network. The data from the cluster members (SNs) is received through the CH and then sent to the RSU that is close to the CH that is most advantageous. IEEE 802.11P is used by the Ssr to send data to the target location. The FCM-Q LEACH-VANET is seen in Figure 1 below.

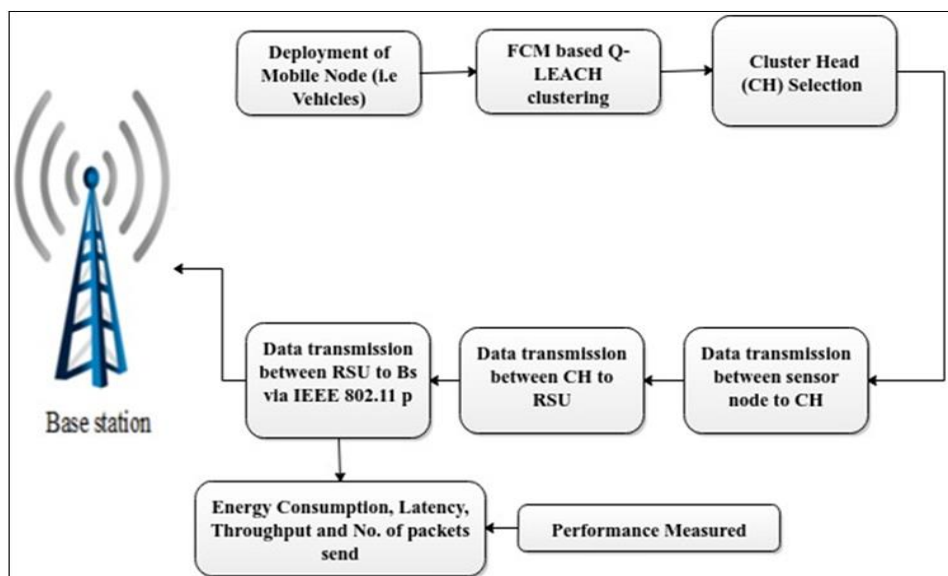


Fig 1 Block Diagram of FCM-Q LEACH VANET

The process of clustering in this FCM-Q LEACH-VANET is carried out using the FCM-based Q-LEACH. For node clustering, the Q-LEACH data aggregation approach is employed. Additionally, Q-LEACH reduces energy usage and increases the usefulness of random connections.

➤ *The FCM-Q LEACH-VANET Technique Entails Six Main Phases, Including*

- Deployment of Mobile Nodes
- Information consolidation using FCM with Q-LEACH Clustering (CH is chosen from each cluster after the groupings are formed within every region).
- Deciding on the appropriate groupings using CH.
- The CH receiving the transfer of data from hubs. Information sent to CHs.
- CHs communicate info to the equipment on the other end of the path.

➤ *Clustering with FCM*

A centralised technique for clustering is the FCM [17]. Based on each SN's location and the chosen centroid, the BS divides the SNs into clusters. This FCM algorithm's primary goal is to address the issue of SNs' allocation across clusters, and it does so by minimising the objective function specified in the following equation (1). Consider an ecosystem which includes M nodes and is divided into c groupings, such as c1, c2, c3, and so on the mean distance from each node and the cluster centre j is represented as dijk and the degree of a node's feeling connected to the group j is expressed as μjk Equation (2) produces the centroids from the required network.(3)defines the membership function of FCM algorithm. The degree μjk of vehicle k respected to cluster is calculated and fuzzified with the real parameter m > 1 as below.

➤ *The following is how the FCM Method is Described as a Method that is Iterative:*

- Choose (n > 1) ; The membership function values
- μjk are initialized, j = 1,2, m; k = 1,2, c.
- Calculate the Euclidean distance dj,k, j = 1,2, m; k = 1,2, c.
- Discover the cluster centres Dk, k = 1,2, c.
- The membership function μjk is updated by equation (3), where j = 1,2, m; k = 1,2, c.

➤ *Cluster-based data aggregation LEACH*

To achieve the hybrid combination of FCM based Q-LEACH clustering, the TDMA cycle of FCM CHs are incorporated in Q-LEACH clustering [18]. In broad terms, data consolidation is the process of combining data from several sources that must be sent to the BS. The system's orderly arrangement is used by the cluster-based aggregated data method. The distribution network is partitioned into four clusters for Q-LEACH, and CHs are chosen from the clusters.

The chosen CHs serve as an information gathering point for sending data to the RSU. There are two types of stage preparation and the stable state portion in Q-LEACH.

➤ *Initial set-up*

In Q-LEACH, the network separates into four quadrants. The coverage of the whole network obtained by using this Q-LEACH. In VANET architecture, there are two sides of roads and each side roads divide as four quadrants by this Q-LEACH. For example, the nodes deploy on the road of 500m*500m field. In the middle of the road, the road side units placed for receiving the data from the CH which is

- M m
- j= jk
- kz
- A1 = a11 + a12 + a13 + a14 (4)
- a1n = A1(xm, ym)

The alteration occurs via WCA, and the supporting head clusters are not the final head assemblies. Every node makes use of the algorithm. Once every member node has sent its position and remaining energy-related data to its auxiliary cluster head, the final cluster heads are determined by WCA. Each auxiliary cluster head notifies the final cluster head and other group participants about the position of the end cluster head. In this stage, the auxiliary cluster's head adjusts using the WCA. I can employ a coefficient of fitness that relies on the residual energy of each node and the location of any junction to the accessory cluster head. We may identify an appropriate location for each sensor node based on its physical factor and after completing all motion steps. The bacteria or every sensor node in the cluster finally sends the extra cluster heads in order and remaining power.

As each node's actual status with regard for Lead will decide its place as the leader person, the network node that is closest to Lead then serves as the ultimate band head.

➤ *Stable State Phase*

The TDMA, all protocol is employed in the stable phase for transmitting information through the router onto the Hc along with from the NH to the RSU for storage. Each node in the auto convey signals into the Nh in accordance with the TDMA, all frequency. Excessive collisions between networks can be prevented by switching a node's mode to either operational or asleep. Input that gets collected via numerous social networking (SN) is collected by VANET before being sent to the RSU. Each time there is a data transfer, the chosen Hc chooses the channel to transport the data through to the RSU. The central station must wait until the following wave before the CH transmits data to an identical RSU. Figure 3 depicts the FCM-Q LEACH-VANET in its stable state phase.

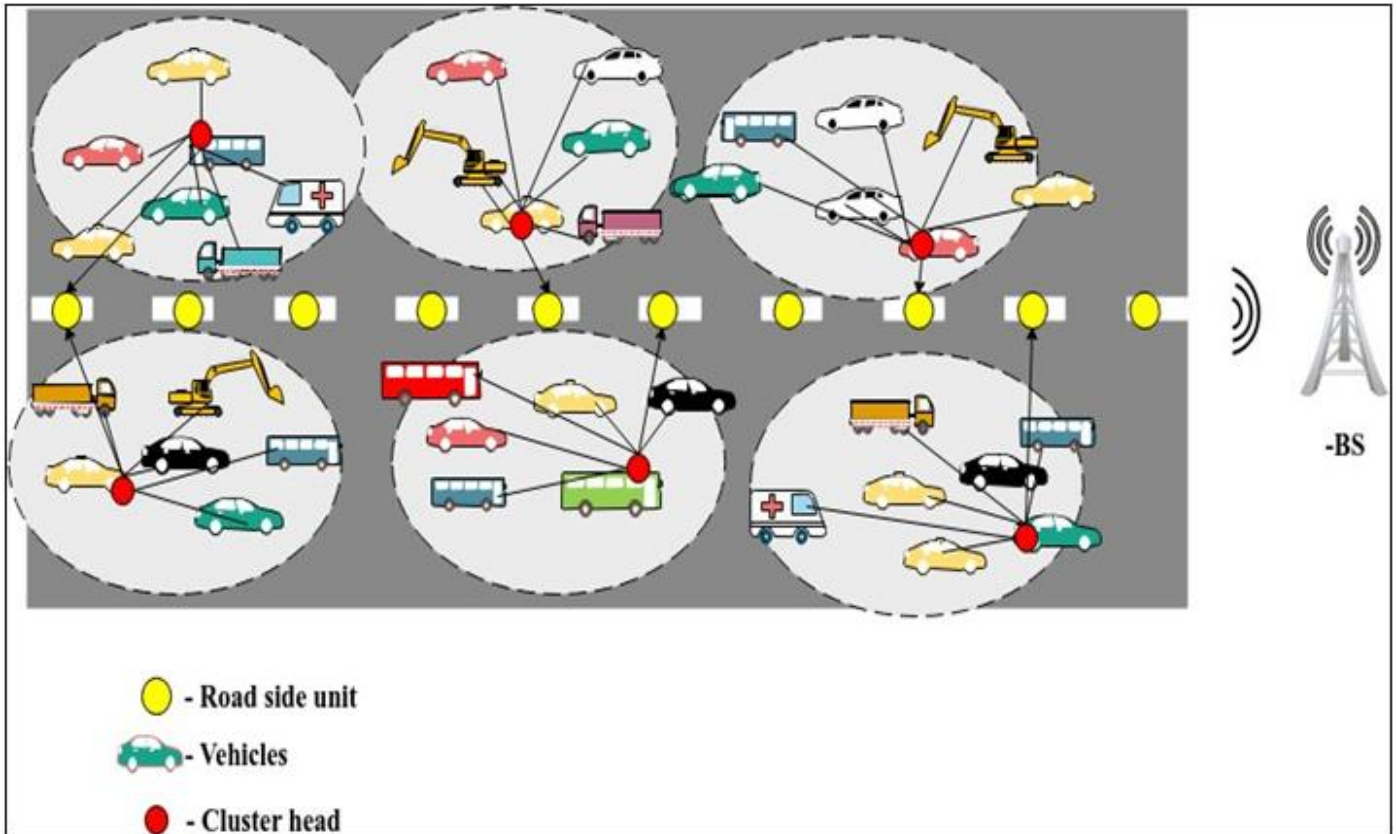


Fig 2 FCM-Q LEACH-VANET Stable State Phase

IV. INTERVENTIONAL INSTALLATION

The MATLAB programme 2016b programme created the FCM-Q LEACH-VANET system (for simulation purposes). The nodes in this VANET design were clustered as a result of the hybridization of FCM and Q-LEACH. The number of nodes used to assess the performance of the FCM-Q LEACH-VANET system ranges from 100 to 400. The simulation settings utilised in the suggested technique are shown in Table 1 below.

Table 1 Simulation-Related Variables

Parameter	Value
Sensor nodes	100, 200, 300 and 400
Road side unit	20
Number of simulation iterations	100
Clustering protocol	FCM with Q-LEACH
Base station location	640, 250
MAC protocol	IEEE 802.11p
Type of channel	Wireless channel
Packet size	3000 bits
Message size	100 bits

➤ **Latency**

Latency in networks is an indicator of the period it typically takes over a data packet to go from a source to a base station. Equation (9) provides the formula for the latencies.

$$L = d_{tot}/S + P_L$$

When, Denotes connection delay, d_{tot} stands for the complete length of the beginning to the BS, which is and S stands for the terminals' frequency.

V. RESULT CONVERSATION

The suggested strategy was put into practise using 10 roadside devices and various SN counts. Interlocking Integrated VANET technology Routing (IDVR) was used to examine the FCM-Q LEACH-VANET performance in order to estimate the effectiveness of the VANET. The complete network's reach is 500*500 m2, and the BS is located at 650, 250. The next sections provide an explanation of the effectiveness metrics that this system analyses.

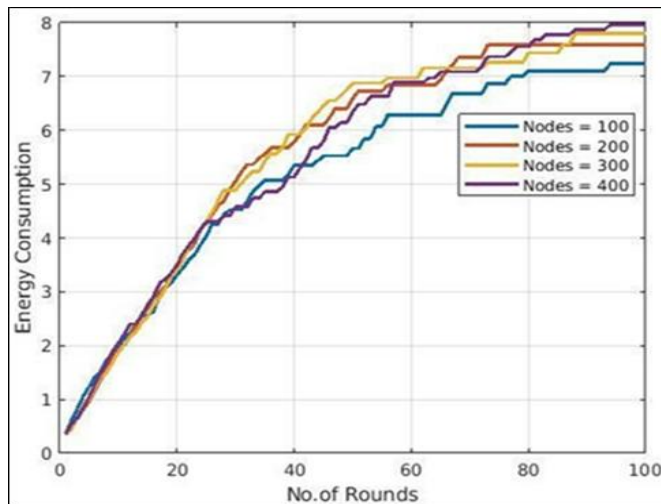


Fig 3 Best Point of Sensor Node in VWCA

VI. CONCLUSION AND FUTURE SCOPE

This study used VANETS to hybridise the FCM-based Q-LEACH clustering method. The best CH found by this clustering from the collection of SNs. The roadside unit that is close to the CHs receives the information collected by these CHs. The IEEE 802.11.p interface was used for the exchange of data between the RSU and the BS. There are a total of 9 sorts of messages that are sent by moving cars, such as at intersections and accidents. The users learn about the nature around the route thanks to the information provided by the BS. This FCM-Q LEACH-VANET's performance was evaluated in terms of energy use, total packets sent, throughput, and network latency. The FCM-Q LEACH-VANET performed better than the IDVR [25] protocol, according to the results, in terms of throughput.

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